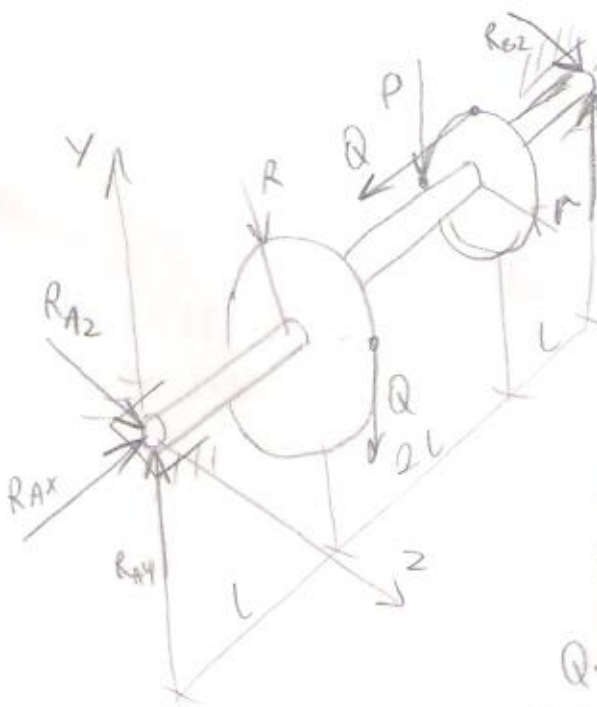


Dan: $Q = 4 \text{ kN}$ ($l = 0,1 \text{ m}$ $r = 0,1 \text{ m}$)
 $R = 2r$



$$\sum F_{ix} = 0 \quad R_{Ax} - Q = 0 \Rightarrow R_{Ax} = Q$$

$$\sum F_{iy} = 0 \quad R_{Ay} - Q - P + R_{By} = 0$$

$$\sum F_{iz} = 0 \quad R_{Az} + R_{Bz} = 0 \Rightarrow R_{Az} = 0$$

$$\sum M_{ix} = 0 \quad Q \cdot R - P \cdot r = 0$$

$$\sum M_{iy} = 0 \quad R_{Bz} \cdot 4l = 0 \Rightarrow R_{Bz} = 0$$

$$\sum M_{iz} = 0 \quad Q \cdot l - Q \cdot r + P \cdot 3l - R_{By} \cdot 4l = 0$$

$$Q \cdot R = P \cdot r$$

$$Q \cdot 2r = P \cdot r / 2$$

$$2Q = P / 2$$

$$P = 2Q$$

$$Q - Q + 3P - 4R_{By} = 0$$

$$4R_{By} = 3P$$

$$4R_{By} = 3 \cdot 2Q$$

$$R_{By} = 1\frac{1}{2} Q$$

$$R_{Ay} - Q - 2Q + 1\frac{1}{2} Q = 0$$

$$R_{Ay} = 3Q - 1\frac{1}{2} Q$$

$$R_{Ay} = 1\frac{1}{2} Q$$

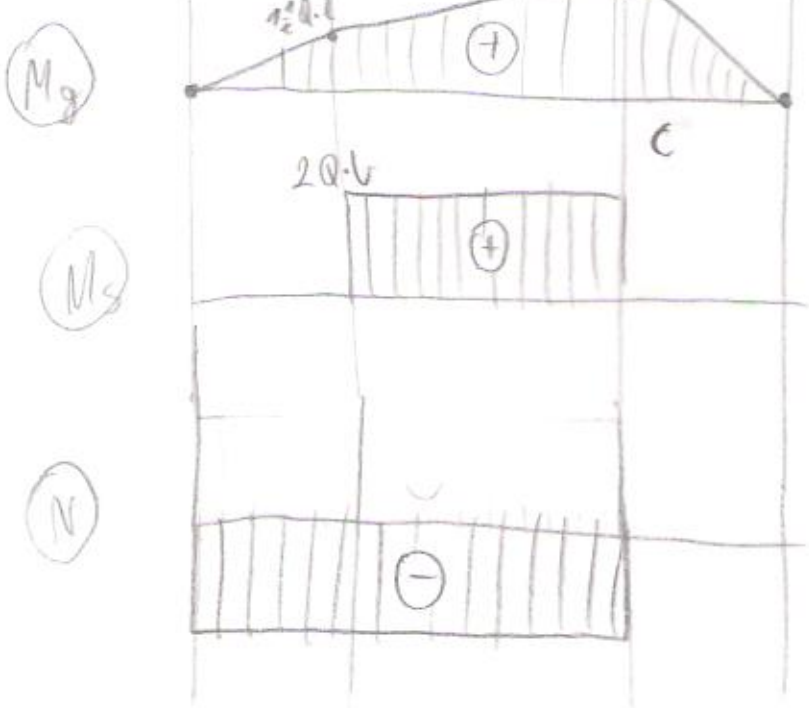
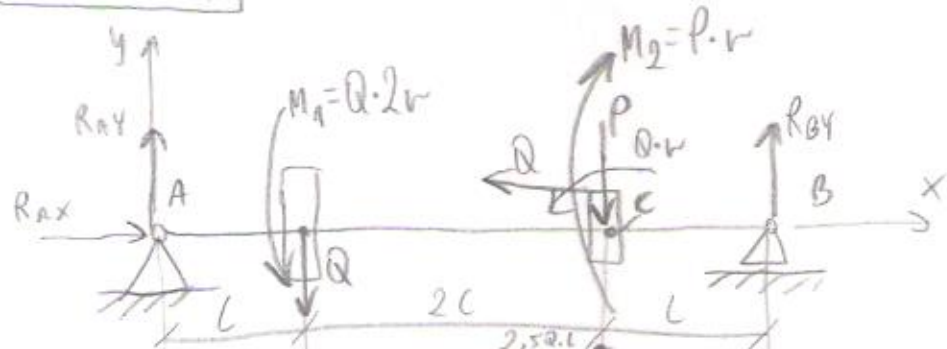
Wiputra Huber

$$\sigma_{zz} = \sqrt{(\sigma_g + \sigma_N)^2 + 3\tau^2}$$

$$\sigma_g = \frac{M_{gmax}}{J_z} \cdot y_{max}$$

$$\sigma_N = \frac{P}{A}$$

$$\tau = \frac{M_s}{J_0} \cdot \rho_{max}$$



$$0 < x < l$$

$$M_g = R_{Ax} \cdot x$$

$$d/dx \ x = 0$$

$$M_g = 0$$

$$d/dx \ x = l$$

$$M_g = R_{Ax} \cdot l$$

$$M_g = 1 \frac{1}{2} Q \cdot l$$

$$N = R_{Ax}$$

$$d/dx \ \begin{cases} x=0 \\ x=l \end{cases} \begin{cases} N = -R_{Ax} \\ N = -Q \end{cases}$$

$$M_s = 0$$

$$l < x < 3l$$

$$M_g = R_{Ax} \cdot x - Q \cdot (x-l)$$

$$N = R_{Ax}$$

$$M_s = M_1$$

$$d/dx \ x = l$$

$$M_g = \frac{1}{2} Q \cdot l$$

$$d/dx \ x = 3l$$

$$M_g = 1 \frac{1}{2} Q \cdot 3l - Q \cdot (3l-l)$$

$$M_g = 4,5 Q \cdot l - 2Q \cdot l$$

$$M_g = 2,5 Q \cdot l$$

$$d/dx \ \begin{cases} x=l \\ x=3l \end{cases} \begin{cases} N = -R_{Ax} \\ N = -Q \end{cases}$$

$$d/dx \ \begin{cases} x=l \\ x=3l \end{cases} \begin{cases} M_s = M_1 \\ M_s = 2 \cdot Q \cdot l \end{cases}$$

$$3l < x < 4l$$

$$M_g = R_{Ax} \cdot x - Q \cdot (x-l) - P \cdot (x-3l) - Q \cdot v$$

$$N = R_{Ax} - Q$$

$$M_s = M_1 - M_2$$

$$d/dx \ x = 3l$$

$$M_g = \frac{1}{2} Q \cdot l \cdot 3l - Q \cdot (3l-l) - P \cdot v$$

$$M_g = 4,5 Q \cdot l - 2Q \cdot l - Q \cdot l$$

$$M_g = 1,5 Q \cdot l$$

$$d/dx \ x = 4l$$

$$M_g = 1 \frac{1}{2} Q \cdot 4l - Q \cdot (4l-l) - P \cdot (4l-3l) - Q \cdot l$$

$$M_g = 6 \cdot Q \cdot l - 3Q \cdot l - P \cdot l - Q \cdot l$$

$$M_g = 6 \cdot Q \cdot l - 3Q \cdot l - 2Q \cdot l - Q \cdot l$$

$$M_g = 6 \cdot Q \cdot l - 6 \cdot Q \cdot l$$

$$M_g = 0$$

$$d/dx \ \begin{cases} x=3l \\ x=4l \end{cases} \begin{cases} N = -R_{Ax} + Q \\ N = -Q - Q \\ N = 0 \end{cases}$$

$$d/dx \ \begin{cases} x=3l \\ x=4l \end{cases} \begin{cases} M_s = M_1 - M_2 \\ M_s = 2Q \cdot v - P \cdot v \\ M_s = 2Q \cdot v - 2Q \cdot v \\ M_s = 0 \end{cases}$$

$$2v = d$$

$$\pi v^2 = \frac{\pi d^2}{4}$$

$$F_g = \frac{M_{g \max}}{J_{zc}} \cdot y_{\max}$$

$$F_g = \frac{2,5 Q \cdot l}{\frac{\pi \cdot d^4}{64}} \cdot \frac{d}{2}$$

$$\tau = \frac{2Q \cdot l}{\frac{\pi d^4}{32}} \cdot \frac{d}{2}$$

$$F_N = \frac{Q}{\frac{\pi d^2}{4}}$$